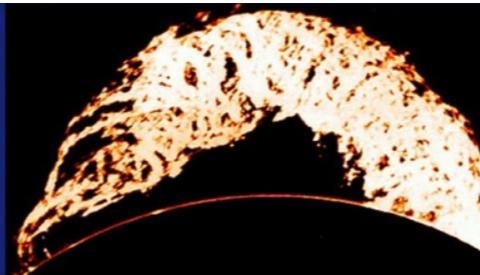
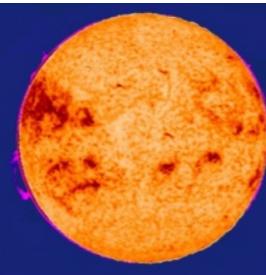
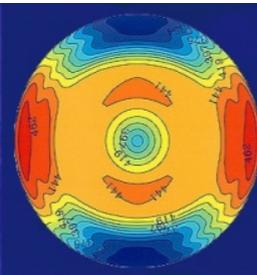


HAO



The Concept of Optimal Calibration

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NCAR

Optimal Modulation

- 2000ApOpt..39.1637D
- Introduces the concept of the efficiency of a modulation scheme.
- Led to the development of the “polychromatic modulator” that is efficient at all wavelengths but (possibly highly) chromatic. DKIST uses these for modulation.

Optimal Calibration

- Can we define a “calibration efficiency” the same way we defined the “modulation efficiency”?
- There is some hope that we can – calibration optics are kind of like inverted modulation optics.

Optimal Calibration

- Short answer: yes.
- Good news: completely analogous to modulation efficiency!
- Those with jetlag may catch up on some sleep now.

Math: Definitions

- \mathbf{O} is the $n \times 4$ modulation matrix (the first rows of the polarimeter Mueller matrix for each of the n states)
- Then the optimal demodulation matrix is $\mathbf{D} = (\mathbf{O}^T \mathbf{O})^{-1} \mathbf{O}^T$
- Efficiencies are $\epsilon_i^2 = 1 / (n (\mathbf{O}^T \mathbf{O})^{-1}_{ii})$.
- Errors in the Stokes vector scale with $1 / \epsilon_i$.

Math:

Calibration Matrix

- Introduce the $4 \times m$ calibration matrix:

$$\mathbf{C} = (\mathbf{I}_{in,1} \ \mathbf{I}_{in,2} \ \dots \ \mathbf{I}_{in,m})$$

- $\mathbf{I}_{meas} = \mathbf{O} \mathbf{C}$

- Now assume we have an \mathbf{E} such that

$$\mathbf{O} = \mathbf{I}_{meas} \mathbf{E} = \mathbf{O} \mathbf{C} \mathbf{E}$$

- \mathbf{E} exists, $\mathbf{C} \mathbf{E} = \mathbf{1}$, and $\mathbf{E} = \mathbf{C}^T (\mathbf{C} \mathbf{C}^T)^{-1}$.

Math:

Error Propagation

- Assume every measurement in \mathbf{I}_{meas} has an error σ . (This isn't true.)
- $\sigma_j^2 = \sigma^2 \sum_k E_{kj}^2$
- Analogously to modulation efficiency, we can now define calibration efficiency as:
$$\eta_j = (m \sum_k E_{kj}^2)^{-1/2}$$
- And we see also that $\underline{\sigma}_j^2 = \sigma^2 / \eta_j^2$

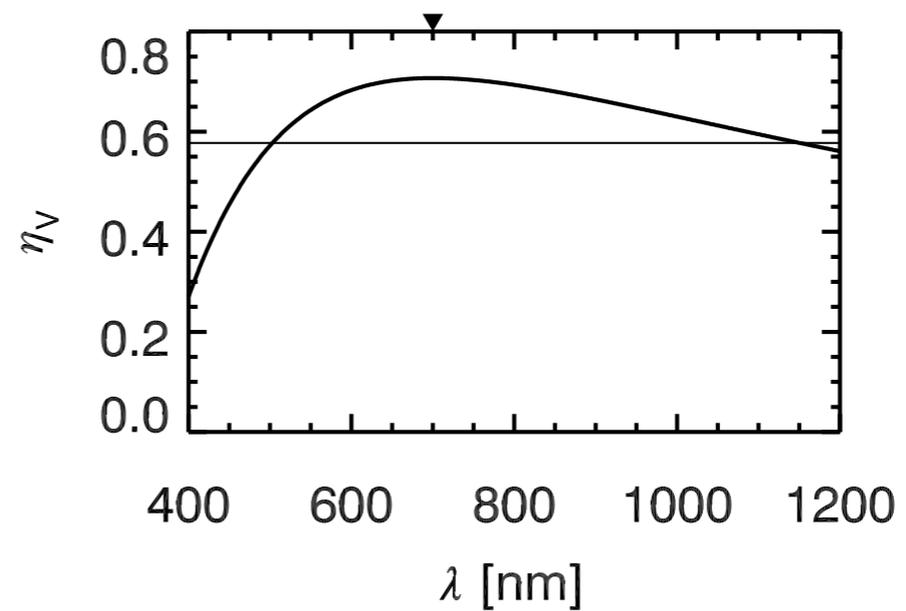
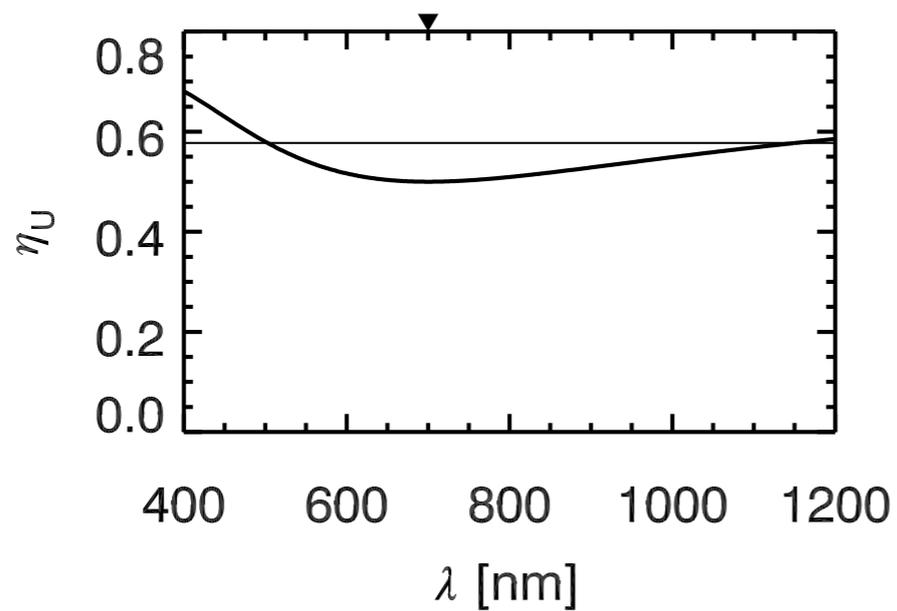
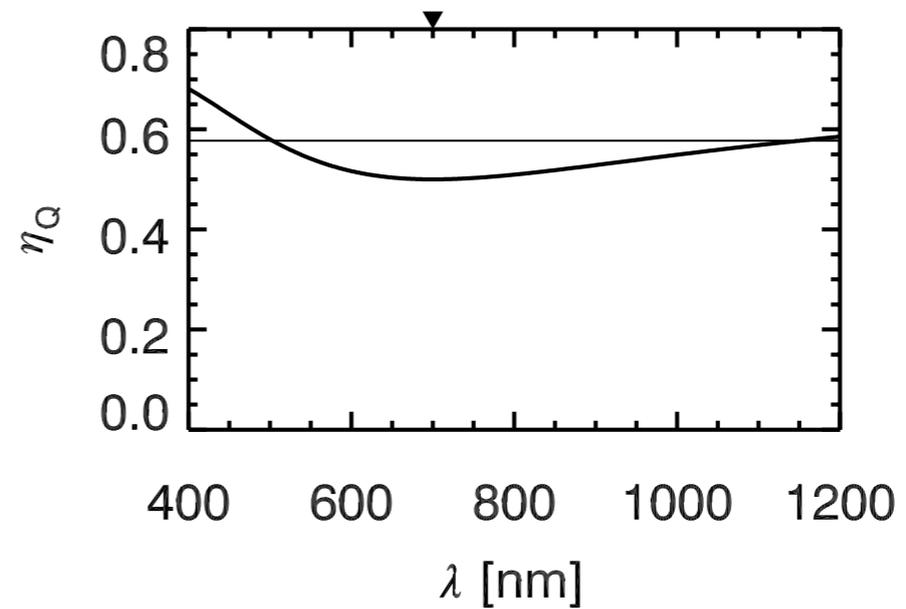
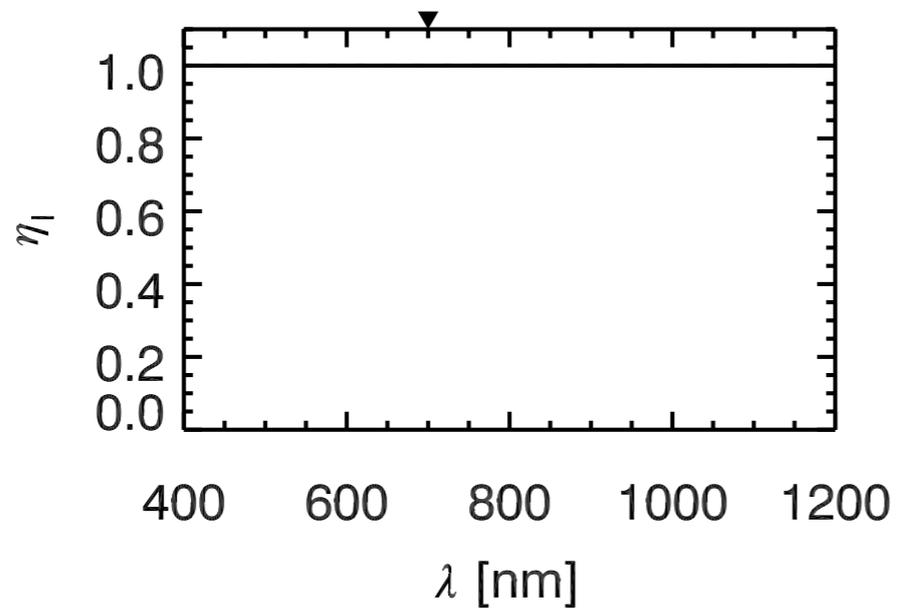
Optimal Calibration

- Notice that this is fully analogous to modulation efficiency. Hence we can follow JCdTI & MC.
- Define $\mathbf{B} = (\mathbf{C} \mathbf{C}^T)$.
- $\eta_i^2 = 1 / (m B_{ii})$
- A more diagonal \mathbf{B} corresponds to a more optimal calibration scheme.

Practical Example

- Calibration package consisting of a perfect polarizer and a perfect $\frac{1}{4}$ -wave retarder at 700 nm.
- Input Stokes vector is unpolarized.
- The retarder fast axis is rotated to 0, 45, 90, and 135 degrees for each of the polarizer positions of 0, 45, 90, and 135 degrees.

Practical Example



Questions and Ideas

- The errors on the components of \mathbf{I}_{meas} are not all the same. What is the consequence?
- We usually don't know what \mathbf{C} is. What is the consequence?
- Can the \mathbf{E} matrix formulation help in the reduction of calibration data for DKIST?
- Can we deterministically find \mathbf{O} ?